eat No.:	Enrolment No.

## **GUJARAT TECHNOLOGICAL UNIVERSITY**

BE – SEMESTER – VI (NEW).EXAMINATION – WINTER 2016

	•	ect Code: 2160910 Date: 26/10/2016	
7	[ime	ect Name: Electrical Drives : 02:30 PM to 05:00 PM Total Marks: 70 ections:	
		<ol> <li>Attempt all questions.</li> <li>Make suitable assumptions wherever necessary.</li> <li>Figures to the right indicate full marks.</li> </ol>	
Q.1	(a) (b)	What is electric drive? Advantages of electrical drive.  Explain drive parameter,  1) Loads with rotational motion.  2) Loads with translational motion.	07 07
Q.2	(a) (b)	Explain type-A and type-B chopper.  Explain the analysis of the PWM half bridge inverter.  OR	07 07
	<b>(b)</b>	Explain the sliding mode control method.	07
Q.3	(a) (b)	Explain the model referencing adaptive control (MARC) method. Explain the torque equation for D.C motor.	07 07
Q.3	(a) (b)	OR  Explain the Dynamic model of DC motor drive.  Explain speed torque characteristics of DC series motor, DC shunt motor and PMDC motor.	07 07
Q.4	(a) (b)	Different between VSI & CSI induction motor drives.  Explain d-q model of induction motor.	07 07
Q.4	(a) (b)	OR  Explain advantages & disadvantages of traction drives.  Explain basic structure of solar and battery powered drives.	07 07
Q.5	(a) (b)	Explain speed torque conventions and multi quadrant operation of drives.  Explain steady-state and transient stability of an electric drive.  OR	07 07
Q.5	(a) (b)	Explain four quadrant chopper (Type-E chopper). Explain single phase semiconductor & half controlled converter.	07 07

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