GUJARAT TECHNOLOGICAL UNIVERSITY

		DE BENNESTER (III(I'E)) EMINIMULTION	DOMINIUM TOLD			
Subj	Subject Code:2171903 Date:27/0					
Subj	ect l	Name:Computer Aided Manufacturing				
Time	e:02:	30 PM TO 05:00 PM	Total Marks: 70)		
Instru	ıction	s:				
	1.	Attempt all questions.				
	2.	Make suitable assumptions wherever necessary.				
	3.	Figures to the right indicate full marks.				
		Abbreviations have usual meaning.				
Q.1	(a)	Give three points each on advantages and disadvanta	ages of CAM.	03		
•	(b)	Describe in short the types of manufacturing system	•	04		
	(c)	Explain open-loop control system used in a CNC sy				
	(0)	diagram (include the drawback and application). Di				
		velocity control loop for a closed-loop control system	<u> </u>	04 07		
		versely control loop for a closed-loop control system				
Q.2	(a)	Draw a block diagram for retrieval type CAPP syste	m.	03		

Q.2 (a) Draw a block diagram for retrieval type CAPP system. (b) Figure 1 shows a 4-axes horizontal machining center. Designate its axes. 04

(c) Explain the principle of recirculating ball screw. Make a table of comparison between a conventional screw and a ball screw regarding load carrying capacity, travel speed, positioning, stiffness, friction, efficiency and maintenance.

OR

- (c) First write a cut planning and then write a part program to drill a pattern of holes on a 15-mm thick plate as shown in Figure 2. Use subprogram method. Cutting parameters are: tool number T02, speed 30 m/min, feed 50 mm/min. (Do not draw the given figure)
- Q.3 (a) When could you state that a manufacturing system is 'flexible'? If there are any tests for checking this, name them.
 - (b) Brief about functions of computers in FMS. (Any four) 04
 - (c) What are the two major functions of tool monitoring systems? Explain various methods adopted for it.

OR

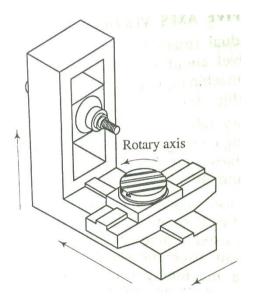
- Q.3 (a) Define PLC. Brief about the relay device components used in it.
 (b) State points on role of manufacturing engineers in the CIM environment.
 (c) Apply the rank order clustering technique to the PFA chart given in Figure
 07
 - (c) Apply the rank order clustering technique to the PFA chart given in Figure 3.
- Q.4 (a) Define load capacity, degree of freedom, work volume for a robot system.
 - (b) Write a brief note on position sensors used in robots.
 (c) Provide a comprehensive list of robot specifications with regard to (a) manipulator and (b) controller.

OR

- Q.4 (a) Explain the PLC architecture using a diagram.
 (b) Enlist benefits of an FMS. State the associated limitations.
 Q.4
 - (c) What are the different work-space configurations of a robot? Explain any two with neat figures.
- Q.5 (a) What do you understand by bill-of-materials and master production 03 schedule as required in an MRP system?
 - (b) What is MRP-II? Explain in brief. 04
 - (c) Elaborate on JIT production systems. How are these usefully associated with FMS?

07

- **Q.5** (a) In block number 60 of a part program a linear interpolation is required to a target point (25.40, 12.50, --10.00) with feed rate 200 mm/min and coolant on. Write this block in fixed sequential format, tab sequential format and word address format. (Coordinates are in millimeters)
 - (b) A 200-step stepper motor is directly connected to a 5-mm pitch ballscrew. Calculate the resolution of the axis. Also calculate number of pulses required to move the axis by a distance of 70.275 mm. What shall be the pulse frequency to the stepper motor in order to achieve a linear velocity of 210 mm/min?
 - (c) Enumerate types of problems commonly encountered in planning and control of production when traditional PPC is employed.



	Parts									
Machines	Α	В	С	D	Ε	F	G	Н	I	
1	1			1				1		
2					1				1	
3			1		1				1	
4		1				1				
5	1							1		
6			1						1	
7		1				1	1			

Figure 1 Figure 3

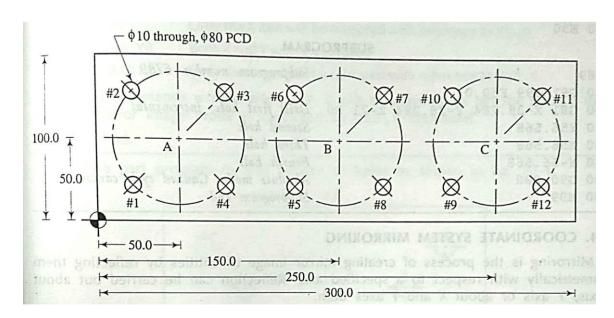


Figure 2 *********

03